

*Para 2010: State of the Art in Scientific and Parallel Computing*

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## Performance Evaluation of Core Numerical Algorithms: a Tool to Measure Instruction Level Parallelism

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DALI Research Project



**UPVD**  
Université de Perpignan Via Domitia



**DALI**  
Digital Architectures et Logiciels Informatiques

# Context and motivation

Aim: **Improve** and validate the **accuracy** of numerical algorithms ...  
... without sacrificing the **running-time** performances

Floating point computation using IEEE-754 arithmetic

A classic problem: I want to double the accuracy of a computed result while running as fast as possible?

A classic answer:

Metric	Eval	AccEval1	AccEval2
Flop count	$2n$	$22n + 5$	$28n + 4$
Flop count ratio	1	$\approx 11$	$\approx 14$
Measured #cycles ratio	1	$2.8 - 3.2$	$8.7 - 9.7$

Flop counts and running-times are not proportional. **Why? Which one trust?**

# Running-time measures: details

Average ratios for polynomials of degree 5 to 200

Working precision: IEEE-754 double precision

		$\frac{\text{CompHorner}}{\text{Horner}}$	$\frac{\text{DDHorner}}{\text{Horner}}$	$\frac{\text{DDHorner}}{\text{CompHorner}}$
Pentium 4, 3.00 GHz (x87 fp unit)	GCC 4.1.2	2.8	8.5	3.0
	ICC 9.1	2.7	9.0	3.4
(sse2 fp unit)	GCC 4.1.2	3.0	8.9	3.0
	ICC 9.1	3.2	9.7	3.4
Athlon 64, 2.00 GHz	GCC 4.1.2	3.2	8.7	3.0
Itanium 2, 1.4 GHz	GCC 4.1.1	2.9	7.0	2.4
	ICC 9.1	1.5	5.9	3.9

Results vary with a factor of 2

Life-period for the significance of these computing environments ?

# How to trust non-reproducible experiment results?

## Measures are mostly non-reproducible

- The execution time of a binary program varies, even using the same data input and the same execution environment.

## Why? Experimental uncertainties

- spoiling events: background tasks, concurrent jobs, OS interrupts
- non deterministic issues: instruction scheduler, branch predictor
- external conditions: temperature of the room
- timing accuracy: no constant cycle period on modern processors (i7, ...)

## Uncertainty increases as computer system complexity does

- architecture issues: multicore, many/multicore, hybrid architectures
- compiler options and its effects

# How to read the current literature?

## Lack of proof, or at least of reproducibility

*Measuring the computing time of summation algorithms in a high-level language on today's architectures is more of a hazard than scientific research.*

*S.M. Rump (SISC, 2009)*

## The picture is blurred: the computing chain is wobbling around

*If we combine all the published speedups (accelerations) on the well known public benchmarks since four decades, why don't we observe execution times approaching to zero?*

*S. Touati (2009)*

## Two separate jobs:

write and prove the algorithm vs. profile and tune one of its implementation

*We do not consider the source code (wrt the execution trace) since it's not clear we understand it enough for tuning the execution analysis.*

*M. Casas (Para 2010, last Sunday during the questions)*

# Outline

- 1 How to choose the fastest algorithm?
- 2 The PerPI Tool
  - Goals and principles
- 3 The PerPI Tool: outputs and first examples
- 4 Conclusion

# Highlight the potential of performance

## General goals

- Understand the algorithm and architecture interaction
- Explain the set of measured running-times of its implementations
- Abstraction wrt the computing system for performance prediction and optimization
- Reproducible results in time and in location
- Automatic analysis

## Our context

- Objects: accurate and core-level **algorithms**: XBLAS, polynomial evaluation
- Tasks: compare algorithms, improve the algorithm while designing it, chose algorithms → architecture, optimize algorithm → architecture

# The PerPI Tool: principles

## Abstract metric: Instruction Level Parallelism

- ILP: the potential of the instructions of a program that can be executed simultaneously
- #IPC for the Hennessy-Patterson ideal machine
- Compilers and processors exploits ILP: superscalar out-of-order execution
- Thin grain parallelism suitable for single node analysis (M. Gerndt, Monday)



# What is ILP?

A synthetic sample:  $e = (a+b) + (c+d)$

x86 binary

	...
i1	mov eax,DWP[ebp-16]
i2	mov edx,DWP[ebp-20]
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Instruction and cycle counting

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	...

Instruction and cycle counting

Cycle 0: i1 i2 i4

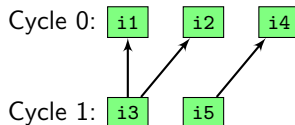
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Instruction and cycle counting



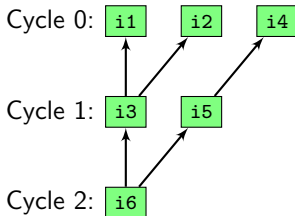
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Instruction and cycle counting



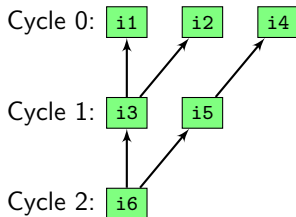
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	...

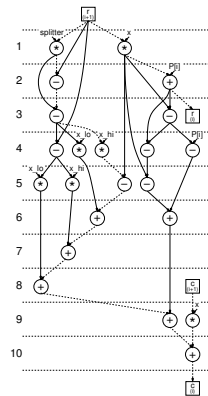
Instruction and cycle counting



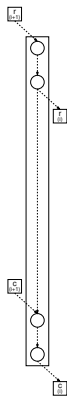
# of instructions = 6, # of cycles = 3  
ILP = # of instructions/# of cycles = 2

# ILP explains why compensated algorithms are fast

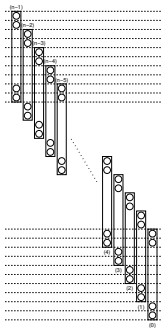
ILP:



(a)



(b)



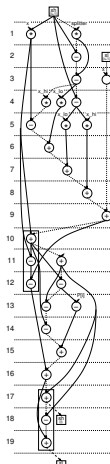
(c)

AccEval

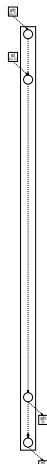
$\approx 11$

AccEval2

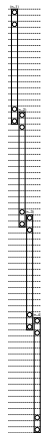
1.65



(a)



(b)



(c)

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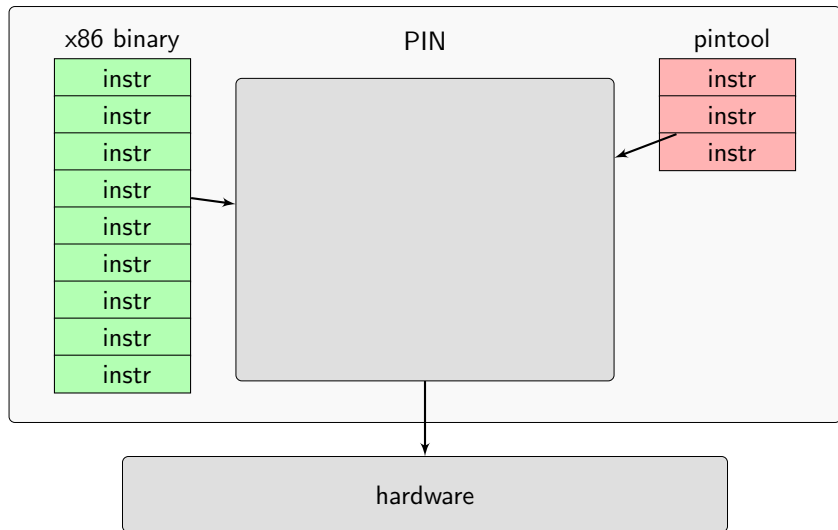
## From ILP analysis to the PerPI tool

- 2007: successful previous pencil-and-paper ILP analysis [PhL-Louvet,2007]
- 2008: prototype within a processor simulation platform (PPC asm)
- 2009: PerPI to analyse and visualise the ILP of x86-coded algorithms
  - Pintool (<http://www.pintool.org>)
  - Input: x86 binary file
  - Outputs: ILP measure, IPC histogram, data-dependency graph



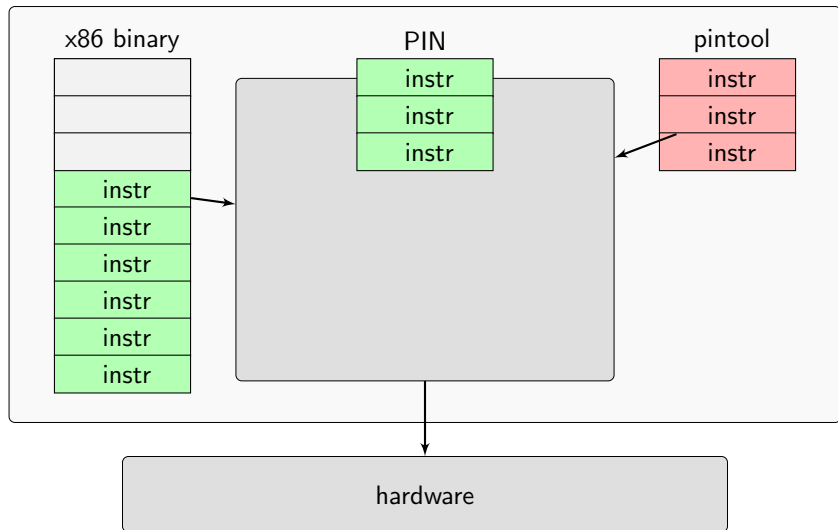
# What is PIN? Dynamic instrumentation

```
$> pin -t pintool -- ./a.out
```



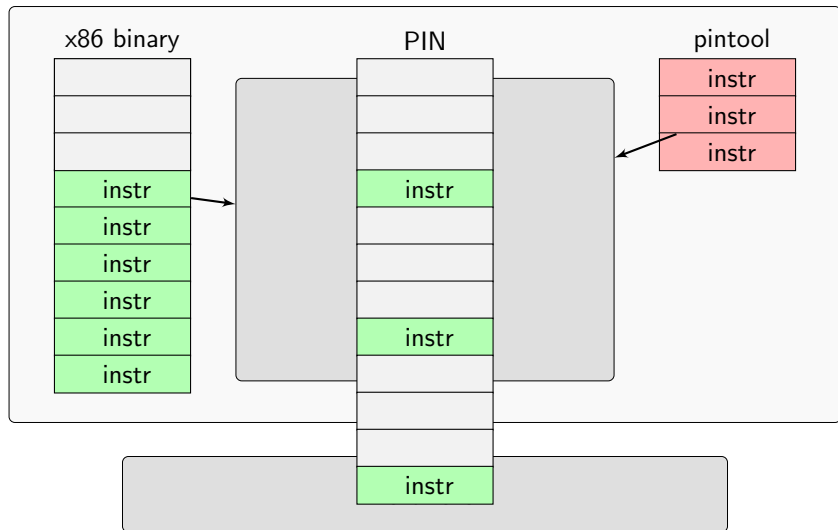
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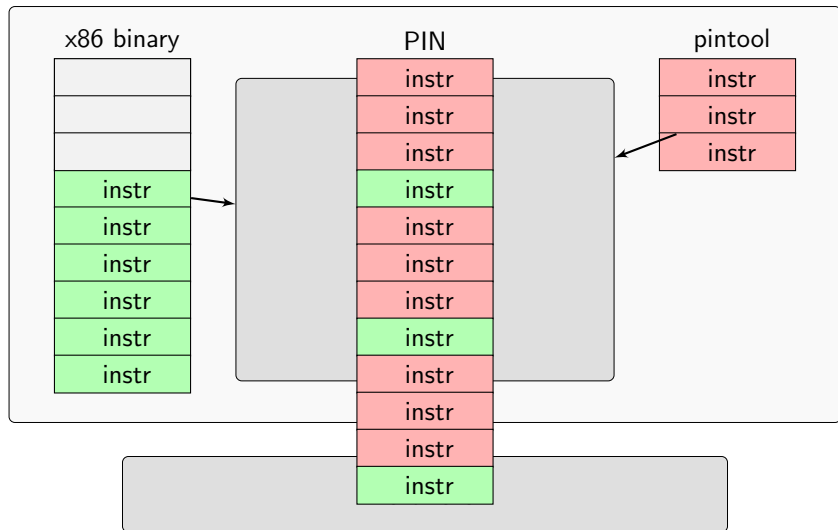
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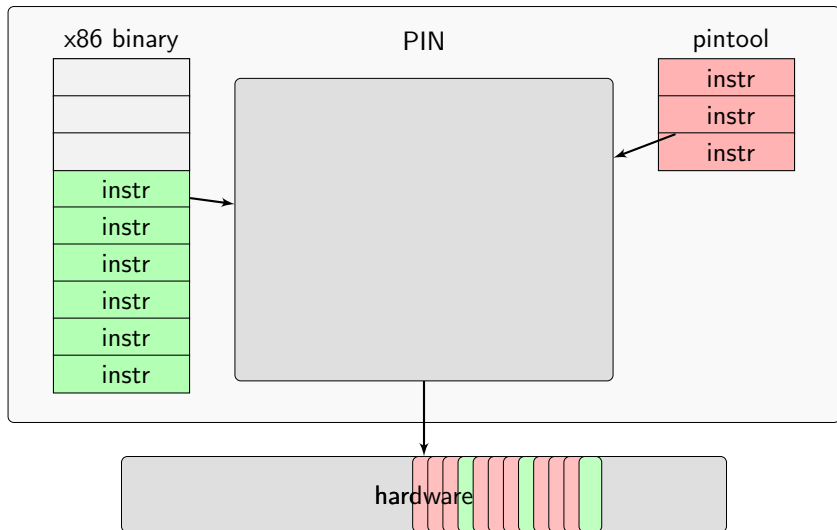
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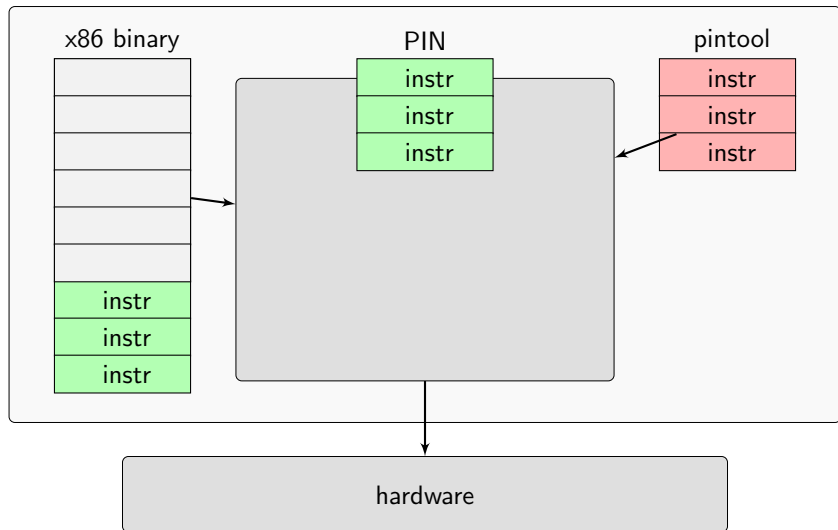
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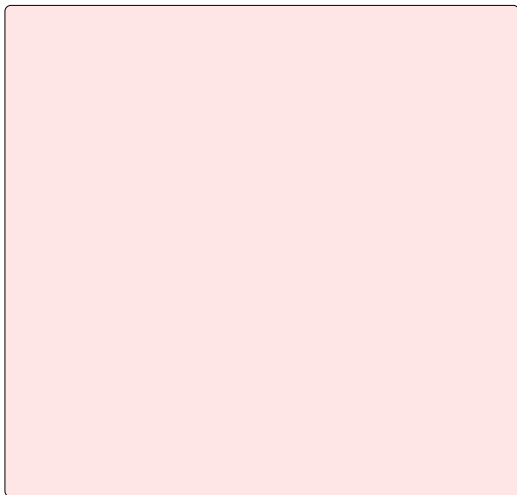
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i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

RC (register cycles)

eax	:	0
ebx	:	0
ecx	:	0
edx	:	0
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 0

nc = 0

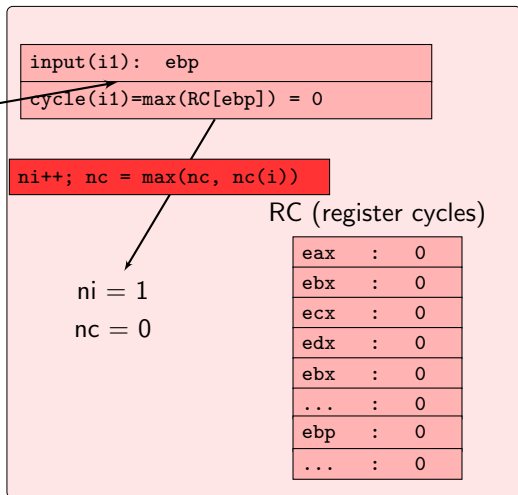
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	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

input(i1): ebp

cycle(i1)=max(RC[ebp]) = 0

output(i1): eax

new cycle(eax)=cycle(i1)+1 = 1

RC (register cycles)

ni = 1

nc = 0

eax	:	1
ebx	:	0
ecx	:	0
edx	:	0
ebx	:	0
...	:	0
ebp	:	0
...	:	0

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edx	:	0
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 1

nc = 0

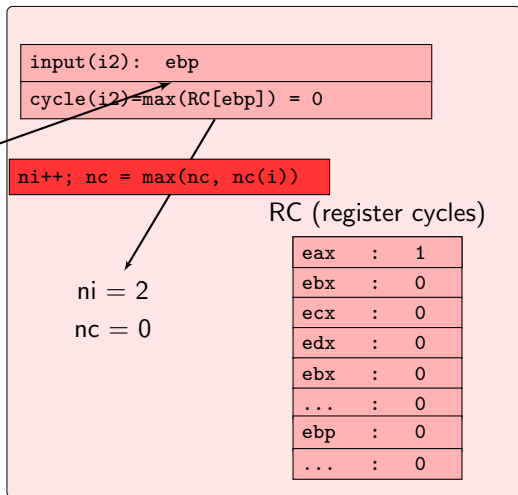
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	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

input(i2):	ebp
cycle(i2)=max(RC[ebp])	= 0
output(i2):	edx
new cycle(edx)=cycle(i2)+1	= 1

RC (register cycles)

ni = 2

nc = 0

eax	:	1
ebx	:	0
ecx	:	0
edx	:	1
ebx	:	0
...	:	0
ebp	:	0
...	:	0

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	...

RC (register cycles)

eax	:	1
ebx	:	0
ecx	:	0
edx	:	1
ebx	:	0
...	:	0
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...	:	0

ni = 2

nc = 0

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i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

input(i3): edx, eax

cycle(i3)=max(RC[edx],RC[eax]) = 1

ni++; nc = max(nc, nc(i))

ni = 3

nc = 1

RC (register cycles)

eax	:	1
ebx	:	0
ecx	:	0
edx	:	1
ebx	:	0
...	:	0
ebp	:	0
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	...

input(i3): edx, eax

cycle(i3)=~~max~~(RC[edx],RC[eax]) = 1

output(i3): edx

new cycle(edx)=cycle(i3)+1 = 2

RC (register cycles)

ni = 3

nc = 1

eax	:	1
ebx	:	0
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

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RC (register cycles)

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ebx	:	0
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 3

nc = 1

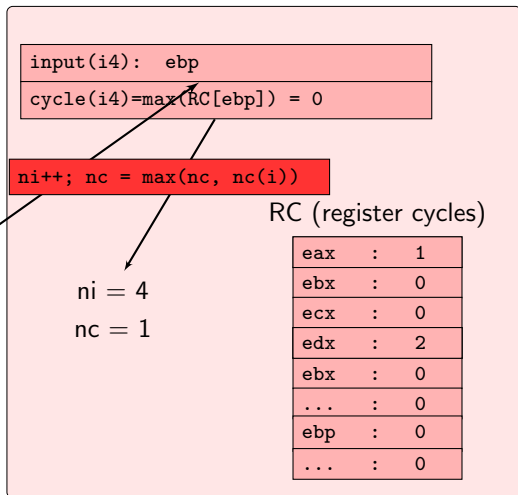
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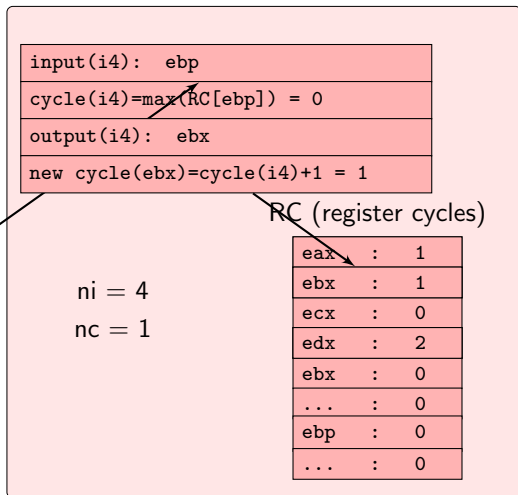
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	call analyse
i6	add edx,ebx
	...

RC (register cycles)

eax	:	1
ebx	:	1
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 4

nc = 1

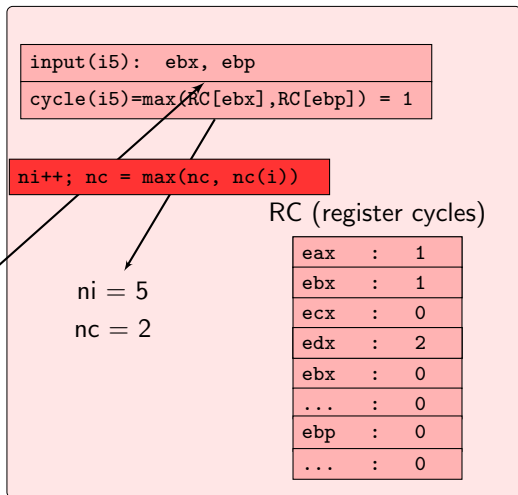
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	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

input(i5): ebx, ebp

cycle(i5)=max(RC[ebx],RC[ebp]) = 1

output(i5): ebx

new cycle(ebx)=cycle(i5)+1 = 2

RC (register cycles)

eax	: 1
ebx	: 2
ecx	: 0
edx	: 2
ebx	: 0
...	: 0
ebp	: 0
...	: 0

ni = 5

nc = 2

# How to compute ILP?

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Analyse routine

x86 binary

	...
	call analyse
i1	mov eax,DWP[ebp-16]
	call analyse
i2	mov edx,DWP[ebp-20]
	call analyse
i3	add edx,eax
	call analyse
i4	mov ebx,DWP[ebp-8]
	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

RC (register cycles)

eax	:	1
ebx	:	2
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 5

nc = 2



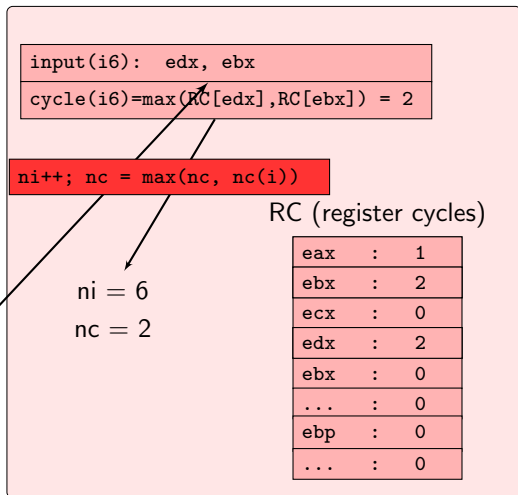
# How to compute ILP?

A synthetic sample:  $e = (a+b) + (c+d)$

Analyse routine

x86 binary

	...
	call analyse
i1	mov eax,DWP[ebp-16]
	call analyse
i2	mov edx,DWP[ebp-20]
	call analyse
i3	add edx,eax
	call analyse
i4	mov ebx,DWP[ebp-8]
	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...



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i4	mov ebx,DWP[ebp-8]
	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

input(i6): edx, ebx

cycle(i6)=max(RC[edx],RC[ebx]) = 2

output(i6): edx

new cycle(edx)=cycle(i6)+1 = 3

ni = 6

nc = 2

RC (register cycles)

eax	: 1
edx	: 3
ecx	: 0
edx	: 2
ebx	: 0
...	: 0
ebp	: 0
...	: 0

# How to compute ILP?

A synthetic sample:  $e = (a+b) + (c+d)$

Analyse routine

x86 binary

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	call analyse
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	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

RC (register cycles)

eax	:	1
edx	:	3
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

ni = 6

nc = 2

# How to compute ILP?

A synthetic sample:  $e = (a+b) + (c+d)$

Analyse routine

x86 binary

	...
	call analyse
i1	mov eax,DWP[ebp-16]
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	call analyse
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	call analyse
i4	mov ebx,DWP[ebp-8]
	call analyse
i5	add ebx,DWP[ebp-12]
	call analyse
i6	add edx,ebx
	...

RC (register cycles)

eax	:	1
edx	:	3
ecx	:	0
edx	:	2
ebx	:	0
...	:	0
ebp	:	0
...	:	0

$ni = 6$

$nc = 2$

$$ILP = 6/3 = 2$$

# Outline

- 1 How to choose the fastest algorithm?
- 2 The PerPI Tool
- 3 The PerPI Tool: outputs and first examples
- 4 Conclusion

# Simulation produces reproducible results

```
start : _start
  start : .plt
    start : __libc_csu_init
      start : _init
        start : call_gmon_start
        stop : call_gmon_start::I[13]::C[9]::ILP[1.44444]
        start : frame_dummy
        stop : frame_dummy::I[7]::C[3]::ILP[2.33333]
        start : __do_global_ctors_aux
        stop : __do_global_ctors_aux::I[11]::C[6]::ILP[1.83333]
      stop : _init::I[41]::C[26]::ILP[1.57692]
    stop : __libc_csu_init::I[63]::C[39]::ILP[1.61538]
  start : main
    start : .plt
      start : .plt
        start : Horner
        stop : Horner::I[5015]::C[2005]::ILP[2.50125]
        start : Horner
        stop : Horner::I[5015]::C[2005]::ILP[2.50125]
        start : Horner
        stop : Horner::I[5015]::C[2005]::ILP[2.50125]
      stop : main::I[20129]::C[7012]::ILP[2.87065]
    start : _fini
      start : __do_global_dtors_aux
      stop : __do_global_dtors_aux::I[11]::C[4]::ILP[2.75]
    stop : _fini::I[23]::C[13]::ILP[1.76923]
```

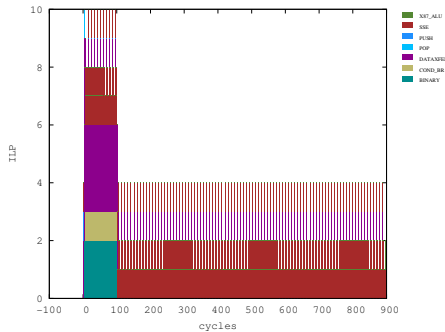
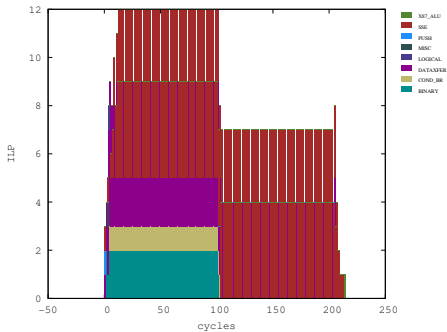
Global ILP ::I[20236]::C[7065]::ILP[2.86426]

# Profile results to compare two algorithms

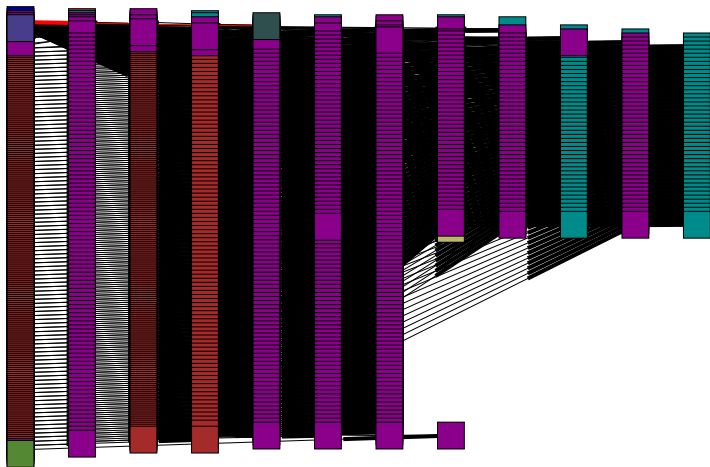
```
start :      _start      (depth: 1 rtn_s_d: 0)
start : __libc_csu_init  (depth: 2 rtn_s_d: 0)
  start :      _init      (depth: 3 rtn_s_d: 0)
    start : call_gmon_start (depth: 4 rtn_s_d: 0)
    stop  : call_gmon_start (depth: 4 rtn_s_d: 0)   I[13]::C[9]::ILP[1.44444]
    start :   frame_dummy  (depth: 4 rtn_s_d: 0)
    stop  :   frame_dummy  (depth: 4 rtn_s_d: 0)   I[7]::C[3]::ILP[2.33333]
    start : __do_global_ctors_aux (depth: 4 rtn_s_d: 0)
    stop  : __do_global_ctors_aux (depth: 4 rtn_s_d: 0)   I[11]::C[6]::ILP[1.8]
  stop  :      _init      (depth: 3 rtn_s_d: 0)   I[41]::C[26]::ILP[1.57692]
stop  : __libc_csu_init  (depth: 2 rtn_s_d: 0)   I[63]::C[39]::ILP[1.61538]
start :      main      (depth: 2 rtn_s_d: 0)
  start :      Horner      (depth: 3 rtn_s_d: 0)
  stop  :      Horner      (depth: 3 rtn_s_d: 0)   I[519]::C[206]::ILP[2.51942]
  start :      CompHorner  (depth: 3 rtn_s_d: 0)
  stop  :      CompHorner  (depth: 3 rtn_s_d: 0)   I[3732]::C[318]::ILP[11.7358]
  start :      DDHorner    (depth: 3 rtn_s_d: 0)
  stop  :      DDHorner    (depth: 3 rtn_s_d: 0)   I[4229]::C[2106]::ILP[2.00807]
stop  :      main      (depth: 2 rtn_s_d: 0)   I[9062]::C[2509]::ILP[3.6118]
start :      _fini      (depth: 2 rtn_s_d: 0)
  start : __do_global_dtors_aux (depth: 3 rtn_s_d: 0)
  stop  : __do_global_dtors_aux (depth: 3 rtn_s_d: 0)   I[11]::C[4]::ILP[2.75]
stop  :      _fini      (depth: 2 rtn_s_d: 0)   I[23]::C[13]::ILP[1.76923]

Global ILP   I[9169]::C[2562]::ILP[3.57884]
```

# Histograms to compare two algorithms







# Instruction dependence graph to compare two algorithms

- New FastAccSum is announced to be faster than AccSum:
- $3n$  vs.  $4n$  flop ( $\times m$  outer iterations) [SISC,2009]

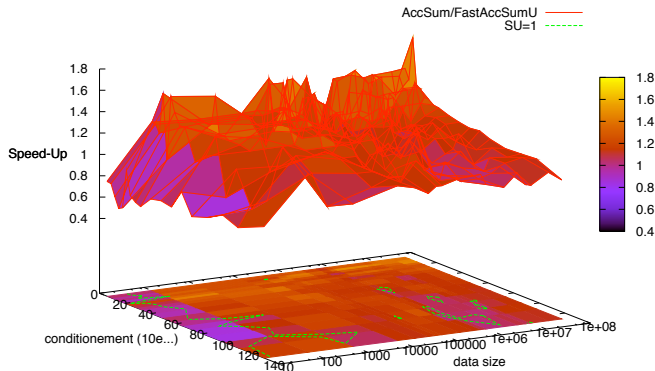
SIEGFRIED M. RUMP

TABLE 6.1  
*Ratio of computing times  $t(\text{AccSum})/t(\text{FastAccSum})$ .*

cond \ $n$	100	300	1000	3000	10,000
$10^6$	1.09	1.18	1.30	1.35	1.33
$10^{16}$	1.22	1.22	1.29	1.30	1.88
$10^{32}$	1.33	1.27	1.45	1.25	1.38
$10^{48}$	1.35	1.43	1.38	1.33	1.47
$10^{60}$	1.25	1.33	1.29	1.27	1.40

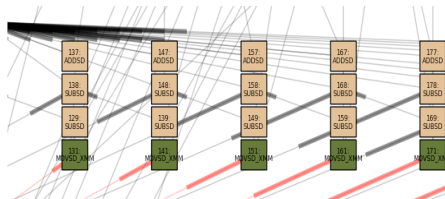
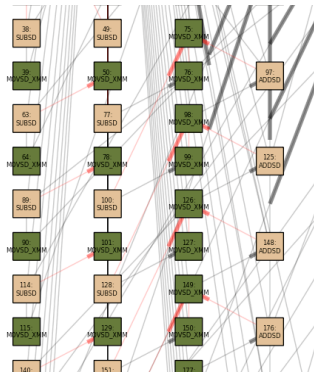
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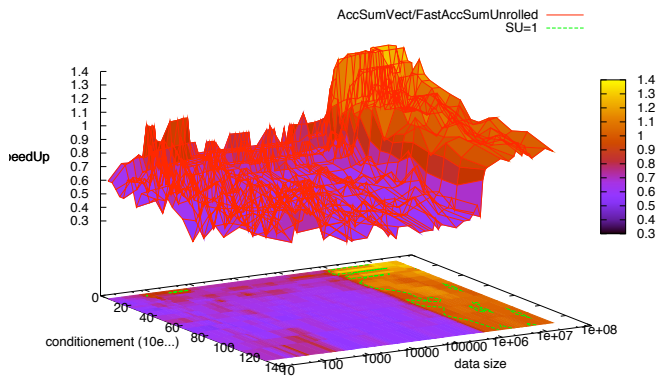
# Instruction dependence graph to compare two algorithms

- New FastAccSum is announced to be faster than AccSum:
- $3n$  vs.  $4n$  flop ( $\times m$  outer iterations) [SISC,2009]
- but AccSum benefits for more ILP



# Instruction dependence graph to compare two algorithms

- New FastAccSum is announced to be faster than AccSum:
- $3n$  vs.  $4n$  flop ( $\times m$  outer iterations) [SISC,2009]
- but AccSum benefits for more ILP
- Let's exploit it!



# Instruction dependence graph to compare two algorithms

- New FastAccSum is announced to be faster than AccSum:

- S.M. Rump is right!

**6. Timing.** In this section we briefly report on some timings. We do this with great hesitation: Measuring the computing time of summation algorithms in a high-level language on today's architectures is more of a hazard than scientific research. The results are hardly predictable and often do not reflect the actual performance.

# This is the end

- 1 How to choose the fastest algorithm?
- 2 The PerPI Tool
- 3 The PerPI Tool: outputs and first examples
- 4 Conclusion**

# Conclusions

## PerPI: a software platform to analyze and visualise ILP

- Useful: a detailed picture of the intrinsic behavior of the algorithm
- Reliable: reproducibility both in time and location
- Realistic: correlation with measured ones
- Exploratory tool: gives us the taste of the behavior of our algorithms within “tomorrow” processors
- Optimisation tool: analyse the effect of some hardware constraints

## Cons ... at the current state

- Work in progress
- Not abstract enough: instruction set dependence
- Assembler program or high level programming language?  
IPC vs. FloPC ?



## Current working list

- Improving the post-processing visualisation
- Make PerPI available on-line and usable as black-box

*The key to performance is to understand the algorithm and the architecture interaction.*

*Fred Gustavson, Para 2010, last Monday.*

*Bo Kågström, Para 2010, last Tuesday.*